

**ABELIAN MONOID ON NEUTROSOPHIC FUZZY MATRICES USING
LUKASIEWICZ DISJUNCTION AND CONJUNCTION OPERATOR****K. Lalitha^{1*}, S. Sarguna²**¹Department of Mathematics, Annamalai University,

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sudhan_17@yahoo.com, sargunaphd21@gmail.com**Abstract**

In this article, we study some of the properties of disjunction and conjunction from Lukasiewicz's type over Neutrosophic fuzzy sets and fuzzy matrices. Nowadays many fields facing the problem in indeterministic situation such as business, medical diagnosis, networking etc., We describe about max,min,min and min,max,max using neutrosophic fuzzy matrices and abelian Monoid on Lukasiewicz disjunction and conjunction are expounded Moreover, the connection between these concepts is established.

Keywords: Disjunction; Conjunction; Lukasiewicz; Neutrosophic fuzzy set; Neutrosophic fuzzy matrices

MSC 2020 No.: 03E72, 15B15

1. Introduction

Intuitionistic Fuzzy Matrix (IFM) was raised by Atanossov.KT(1986). Samarandache(2005) extended many ideas in Neutrosophic Fuzzy Matrices (NFM). Elements of NFM is in the form of triplets . Each elements of neutrosophic fuzzy set is belong to $[0,1]$. They are fair one, unfair and indeterministic. Sum of these three should lies between 0 and 3. Khan SK et al. acquired the troop of intuitionistic fuzzy matrix. Pal M, Shyamal AK (2002)explained about Notes on Intuitionistic fuzzy sets. Kim, K. H. and Roush, R.W(1980) deals with generalized fuzzy matrices. The method of Lukasiewicz was brought by T.Muthuraji, S.Sriram(2015). D. Venkatesan and S.Sriram(2019) established Lukaseiwicz disjunction and conjunction operations over pythagorean fuzzy matrices. Vanmathi.N et al. brought up the ideas over split up of NFMs. Murugadas.P, Balasubramaniyan.K (2019) described the concepts of decomposition of Neutrosophic fuzzy matrices. Atanossov K, Tcvetkok R(2010)tells of on Lukaseiwicz intuitionistic fuzzy disjunction and conjunction. Lalitha. K, Buvanewari. N raised the ideas of few equalities concatenated with intuitionistic fuzzy matrices. Muthuraji et al. (2016) obtained a decomposition of intuitionistic fuzzy matrices. Sriram and Boobalan (2016) studied the properties of algebraic sum and algebraic product of intuitionistic fuzzy matrices and prove that the set of all intuitionistic fuzzy matrices form a commutative monoid using Implication Operator. and established in neutrosophic fuzzy matrix.These two operations are proved under commutative monoid in NFM. In chapter 2 we mentioned the prelims. In

chapter 3 explicate about Lukasiewicz disjunction and conjunction in NFM. We dispute some concepts of Lukasiewicz disjunction and Lukasiewicz conjunction.

2. Preliminaries

Definition 2.1[6].

Let Γ be a neutrosophic fuzzy set on the universal set X . It is defined as $\Gamma = (\langle \gamma_A, \gamma_I, \gamma_F \rangle)$. such that $\gamma_A, \gamma_I, \gamma_F: X \rightarrow (0, 1^+)$ Where $0 \leq \gamma_A + \gamma_I + \gamma_F \leq 3$. Where $\gamma_A, \gamma_I, \gamma_F$ denotes the truthness, indeterminancy, falsity respectively.

Definition 2.2[6].

Each element of Neutrosophic fuzzy matrix is defined as $\Gamma = (\langle \gamma_{A_{dk}}, \gamma_{I_{dk}}, \gamma_{F_{dk}} \rangle)$. Whose values of $\gamma_{A_{dk}}, \gamma_{I_{dk}}, \gamma_{F_{dk}}$ are non-negative real numbers which belongs to $[0,1]$ and fulfilling the state $0 \leq \gamma_{A_{dk}} + \gamma_{I_{dk}} + \gamma_{F_{dk}} \leq 3$ for every d, k .

Definition 2.3.

We introduce Lukasiewicz conjunction and disjunction form using neutrosophic fuzzy sets.

$$\Gamma = (\langle \gamma_{A_{dk}}, \gamma_{I_{dk}}, \gamma_{F_{dk}} \rangle)$$

$$\Psi = (\langle \psi_{A_{dk}}, \psi_{I_{dk}}, \psi_{F_{dk}} \rangle).$$

$$\Gamma \vee_L^* \Psi = (\langle \max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} - 1), \min(1, \gamma_{I_{dk}} + \psi_{I_{dk}}), \min(1, \gamma_{F_{dk}} + \psi_{F_{dk}}) \rangle)$$

$$\Gamma \wedge_L^* \Psi = (\langle \min(1, \gamma_{A_{dk}} + \psi_{A_{dk}}), \max(0, \gamma_{I_{dk}} + \psi_{I_{dk}} - 1), \max(0, \gamma_{F_{dk}} + \psi_{F_{dk}} - 1) \rangle)$$

Definition 2.4[6].

Let $\Gamma, \Psi \in \mathcal{F}_{mn}$

(i) If $\Gamma \geq \Psi$ iff $\gamma_{A_{dk}} \geq \psi_{A_{dk}} ; \gamma_{I_{dk}} \leq \psi_{I_{dk}} ; \gamma_{F_{dk}} \leq \psi_{F_{dk}}$.

(ii) $(\langle \max(\gamma_{A_{dk}}, \psi_{A_{dk}}), \min(\gamma_{I_{dk}}, \psi_{I_{dk}}), \min(\gamma_{F_{dk}}, \psi_{F_{dk}}) \rangle) = \Gamma \vee \Psi$

(iii) $(\langle \min(\gamma_{A_{dk}}, \psi_{A_{dk}}), \max(\gamma_{I_{dk}}, \psi_{I_{dk}}), \max(\gamma_{F_{dk}}, \psi_{F_{dk}}) \rangle) = \Gamma \wedge \Psi$

(iv) $(\langle \gamma_{F_{dk}}, 1 - \gamma_{I_{dk}}, \gamma_{A_{dk}} \rangle) = \Gamma^c$ (or) $(\langle 1 - \gamma_{F_{dk}}, 1 - \gamma_{I_{dk}}, \gamma_{A_{dk}} \rangle) = \Gamma^c$ or $(\langle \gamma_{F_{dk}}, \gamma_{I_{dk}}, \gamma_{A_{dk}} \rangle) = \Gamma^c$

3. Some results on NFMs

Definition 3.1[6].

$\Gamma = (\langle \gamma_{A_{dk}}, \gamma_{I_{dk}}, \gamma_{F_{dk}} \rangle)$ is said to be neutrosophic fuzzy matrix. We define

(i) Γ is symmetric iff $\Gamma = \Gamma^T$ i.e., $(\langle \gamma_{A_{dk}}, \gamma_{I_{dk}}, \gamma_{F_{dk}} \rangle) = (\langle \gamma_{A_{kd}}, \gamma_{I_{kd}}, \gamma_{F_{kd}} \rangle)$.

(ii) Γ is reflexive iff $(\langle \gamma_{A_{dd}}, \gamma_{I_{dd}}, \gamma_{F_{dd}} \rangle) = (\langle 1, 0, 0 \rangle)$

(iii) Γ is irreflexive iff $(\langle \gamma_{A_{dd}}, \gamma_{I_{dd}}, \gamma_{F_{dd}} \rangle) = (\langle 0, 1, 1 \rangle)$

(iv) Γ is weakly irreflexive iff $(\langle \gamma_{A_{dd}}, \gamma_{I_{dd}}, \gamma_{F_{dd}} \rangle) \geq (\langle \gamma_{A_{dk}}, \gamma_{I_{dk}}, \gamma_{F_{dk}} \rangle) \forall d, k$.

(v) Γ is transitive $\Gamma^2 \leq \Gamma$

(vi) Γ is idempotent iff $\Gamma^2 = \Gamma$

(vii) Γ is nearly irreflexive if $(\langle \gamma_{A_{dd}}, \gamma_{I_{dd}}, \gamma_{F_{dd}} \rangle) \leq (\langle \gamma_{A_{dk}}, \gamma_{I_{dk}}, \gamma_{F_{dk}} \rangle) \forall d, k$.

Proposition 3.2.

Let Γ and Ψ be any two NFMs. The following conditions are satisfied.

- (i) If Γ and Ψ are reflexive then $\Gamma \vee_L^* \Psi$ and $\Gamma \wedge_L^* \Psi$ are reflexive.
- (ii) If Γ and Ψ are irreflexive then $\Gamma \vee_L^* \Psi$ and $\Gamma \wedge_L^* \Psi$ are irreflexive.
- (iii) If Γ and Ψ are symmetric then $\Gamma \vee_L^* \Psi$ and $\Gamma \wedge_L^* \Psi$ are symmetric.
- (iv) If Γ and Ψ are nearly irreflexive then $\Gamma \vee_L^* \Psi$ and $\Gamma \wedge_L^* \Psi$ are nearly irreflexive.

Proof:

By the definition of reflexive

$$\Gamma = (\langle \gamma_{A_{dd}}, \gamma_{I_{dd}}, \gamma_{F_{dd}} \rangle) = (\langle 1, 0, 0 \rangle)$$

$$\Psi = (\langle \psi_{A_{dd}}, \psi_{I_{dd}}, \psi_{F_{dd}} \rangle) = (\langle 1, 0, 0 \rangle)$$

$$\begin{aligned} (i) \Gamma \vee_L^* \Psi &= (\langle \max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} - 1), \min(1, \gamma_{I_{dk}} + \psi_{I_{dk}}), \min(1, \gamma_{F_{dk}} + \psi_{F_{dk}}) \rangle) \\ &= (\langle \max(0, 1 + 1 - 1), \min(1, 0 + 0), \min(1, 0 + 0) \rangle) \\ &= (\langle 1, 0, 0 \rangle) \end{aligned}$$

$$\begin{aligned} (ii) \Gamma \wedge_L^* \Psi &= \\ &(\langle \min(1, \gamma_{A_{dk}} + \psi_{A_{dk}}), \max(0, \gamma_{I_{dk}} + \psi_{I_{dk}} - 1), \max(0, \gamma_{F_{dk}} + \psi_{F_{dk}} - 1) \rangle) \\ &= (\langle \min(1, 1), \max(0, 0 + 0 - 1), \max(0, 0 + 0 - 1) \rangle) \\ &= (\langle 1, 0, 0 \rangle) \end{aligned}$$

Therefore (i) and (ii) are proved.

(iii) Given Γ and Ψ are symmetric.

$$\begin{aligned} (\langle \gamma_{A_{dk}}, \gamma_{I_{dk}}, \gamma_{F_{dk}} \rangle) &= (\langle \gamma_{A_{kd}}, \gamma_{I_{kd}}, \gamma_{F_{kd}} \rangle) \\ (\langle \psi_{A_{dk}}, \psi_{I_{dk}}, \psi_{F_{dk}} \rangle) &= (\langle \psi_{A_{kd}}, \psi_{I_{kd}}, \psi_{F_{kd}} \rangle) \end{aligned}$$

Let $Y = \Gamma \vee_L^* \Psi$ and $T = \Gamma \wedge_L^* \Psi$

$$\text{Where } Y = (\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle)$$

$$T = (\langle \tau_{A_{dk}}, \tau_{I_{dk}}, \tau_{F_{dk}} \rangle)$$

$$\begin{aligned} (\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) &> \\ &= (\langle \max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} - 1), \min(1, \gamma_{I_{dk}} + \psi_{I_{dk}}), \min(1, \gamma_{F_{dk}} + \psi_{F_{dk}}) \rangle) \end{aligned}$$

Case i)

If $\gamma_{A_{dk}} + \psi_{A_{dk}} \geq 1$ then $\gamma_{A_{dk}} + \psi_{A_{dk}} - 1 \geq 0$

Therefore $\max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} - 1) = \gamma_{A_{dk}} + \psi_{A_{dk}} - 1$

If $\gamma_{I_{dk}} + \psi_{I_{dk}} \geq 1$ and $\gamma_{F_{dk}} + \psi_{F_{dk}} \geq 1$ then, $\min(1, \gamma_{I_{dk}} + \psi_{I_{dk}}) = 1$

And $\min(1, \gamma_{F_{dk}} + \psi_{F_{dk}}) = 1$

$$\begin{aligned} \text{Then } (\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) &= (\langle \gamma_{A_{dk}} + \psi_{A_{dk}} - 1, 1, 1 \rangle) \\ &= (\langle \gamma_{A_{kd}} + \psi_{A_{kd}} - 1, 1, 1 \rangle) \\ (\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) &= (\langle v_{A_{kd}}, v_{I_{kd}}, v_{F_{kd}} \rangle) \end{aligned} \tag{3.1}$$

Case 1.1)

If $\gamma_{A_{dk}} + \psi_{A_{dk}} \geq 1$ then $\gamma_{A_{dk}} + \psi_{A_{dk}} - 1 \geq 0$

And $\gamma_{I_{dk}} + \psi_{I_{dk}} < 1$, $\gamma_{F_{dk}} + \psi_{F_{dk}} < 1$

$$(\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) = (\langle \gamma_{A_{dk}} + \psi_{A_{dk}} - 1, \gamma_{I_{dk}} + \psi_{I_{dk}}, \gamma_{F_{dk}} + \psi_{F_{dk}} \rangle)$$

$$\begin{aligned}
 &= (\gamma_{A_{kd}} + \psi_{A_{kd}} - 1, \gamma_{I_{kd}} + \psi_{I_{kd}}, \gamma_{F_{kd}} + \psi_{F_{kd}}) \\
 &= (\langle v_{A_{kd}}, v_{I_{kd}}, v_{F_{kd}} \rangle)
 \end{aligned} \tag{3.2}$$

Case 2)

If $\gamma_{A_{dk}} + \psi_{A_{dk}} < 1$ then $\gamma_{A_{dk}} + \psi_{A_{dk}} - 1 < 0$

And $\gamma_{I_{dk}} + \psi_{I_{dk}} > 1, \gamma_{F_{dk}} + \psi_{F_{dk}} > 1$

$$\begin{aligned}
 (\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) &= (0, 1, 1) \\
 &= (\langle v_{A_{kd}}, v_{I_{kd}}, v_{F_{kd}} \rangle)
 \end{aligned}$$

(3.3)

Case 2.1)

If $\gamma_{A_{dk}} + \psi_{A_{dk}} < 1$ then $\gamma_{A_{dk}} + \psi_{A_{dk}} - 1 < 0$

And $\gamma_{I_{dk}} + \psi_{I_{dk}} < 1, \gamma_{F_{dk}} + \psi_{F_{dk}} < 1$

$$\begin{aligned}
 (\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) &= (0, \gamma_{I_{dk}} + \psi_{I_{dk}}, \gamma_{F_{dk}} + \psi_{F_{dk}}) \\
 &= (0, \gamma_{I_{kd}} + \psi_{I_{kd}}, \gamma_{F_{kd}} + \psi_{F_{kd}})
 \end{aligned} \tag{3.4}$$

From (2),(3),(4),(5)

$$(\langle \zeta_{t_{rs}}, \vartheta_{t_{rs}}, \xi_{t_{rs}} \rangle) = (\langle \zeta_{t_{sr}}, \vartheta_{t_{sr}}, \xi_{t_{sr}} \rangle)$$

$\Rightarrow \Gamma \vee_L^* \Psi$ is symmetric

Similarly, we can prove $T = \Gamma \wedge_L^* \Psi$

$\Gamma \wedge_L^* \Psi$ is symmetric.

(iv) Since Γ and Ψ are nearly irreflexive

$$(\langle \gamma_{A_{dd}}, \gamma_{I_{dd}}, \gamma_{F_{dd}} \rangle) \leq (\langle \gamma_{A_{dk}}, \gamma_{I_{dk}}, \gamma_{F_{dk}} \rangle)$$

$$(\langle \psi_{A_{dd}}, \psi_{I_{dd}}, \psi_{F_{dd}} \rangle) \leq (\langle \psi_{A_{dk}}, \psi_{I_{dk}}, \psi_{F_{dk}} \rangle)$$

Let $\Gamma \vee_L^* \Psi$ be $(\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle)$

$$(\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) =$$

$$(\langle \max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} - 1), \min(1, \gamma_{I_{dk}} + \psi_{I_{dk}}), \min(1, \gamma_{F_{dk}} + \psi_{F_{dk}}) \rangle) \tag{3.5}$$

$$(\langle v_{A_{dd}}, v_{I_{dd}}, v_{F_{dd}} \rangle)$$

$$= (\langle \max(0, \gamma_{A_{dd}} + \psi_{A_{dd}} - 1), \min(1, \gamma_{I_{dd}} + \psi_{I_{dd}}), \min(1, \gamma_{F_{dd}} + \psi_{F_{dd}}) \rangle)$$

$$\gamma_{A_{dd}} \leq \gamma_{A_{dk}} \quad \text{and} \quad \psi_{A_{dd}} \leq \psi_{A_{dk}}$$

$$\max(0, \gamma_{A_{dd}} + \psi_{A_{dd}} - 1) \leq \max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} - 1) \tag{3.6}$$

Similarly,

$$\min(1, \gamma_{I_{dd}} + \psi_{I_{dd}}) \geq \min(1, \gamma_{I_{dk}} + \psi_{I_{dk}}) \tag{3.7}$$

$$\min(1, \gamma_{F_{dd}} + \psi_{F_{dd}}) \geq \min(1, \gamma_{F_{dk}} + \psi_{F_{dk}}) \tag{3.8}$$

From (3.6),(3.7),(3.7=3.8)

$$(\langle v_{A_{dd}}, v_{I_{dd}}, v_{F_{dd}} \rangle) \leq (\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle)$$

$\Gamma \vee_L^* \Psi$ is nearly irreflexive, $\Gamma \wedge_L^* \Psi$ is nearly irreflexive.

Proposition 3.3.

Let Γ be NFM, $\Gamma \in \mathcal{F}_{mn}$

- (i) $I_n \wedge_L^* (\Gamma \vee_L^* \Gamma^T)$ is symmetric
- (ii) $I_n \wedge_L^* (\Gamma \vee_L^* \Gamma^T)$ is reflexive
- (iii) $I_n \wedge_L^* (\Gamma \vee_L^* \Gamma^T) = I_n \vee (\Gamma \vee_L^* \Gamma^T)$

Proof:

(i) Let $\Gamma = (\langle \gamma_{A_{dk}}, \gamma_{I_{dk}}, \gamma_{F_{dk}} \rangle)$

$\Gamma^T = (\langle \gamma_{A_{kd}}, \gamma_{I_{kd}}, \gamma_{F_{kd}} \rangle)$.

$$\langle \max(0, \gamma_{A_{dk}} + \gamma_{A_{kd}} - 1), \min(1, \gamma_{I_{dk}} + \gamma_{I_{kd}}), \min(1, \gamma_{F_{kd}} + \gamma_{F_{dk}}) \rangle = T$$

$$T = (\Gamma \vee_L^* \Gamma^T)$$

Where $T = (\langle \tau_{A_{dk}}, \tau_{I_{dk}}, \tau_{F_{dk}} \rangle)$

$\Xi = (\langle \xi_{A_{dk}}, \xi_{I_{dk}}, \xi_{F_{dk}} \rangle)$

$= I_n \wedge_L^* (\Gamma \vee_L^* \Gamma^T)$

$I_n \wedge_L^* (\Gamma \vee_L^* \Gamma^T)$

$$= \begin{cases} (\min(1, 1 + \tau_{A_{dk}}), \max(0, 0 + \tau_{I_{dk}} - 1), \max(0, 0 + \tau_{F_{dk}} - 1)) & \text{if } d = k \\ (\min(1, 0 + \tau_{A_{dk}}), \max(0, 1 + \tau_{I_{dk}} - 1), \max(0, 1 + \tau_{F_{dk}} - 1)) & \text{if } d \neq k \end{cases}$$

If $d = k$

$$\langle \xi_{A_{dk}}, \xi_{I_{dk}}, \xi_{F_{dk}} \rangle = (\langle \min(1, 1 + \tau_{A_{dk}}), \max(0, 0 + \tau_{I_{dk}} - 1), \max(0, 0 + \tau_{F_{dk}} - 1) \rangle)$$

$$\langle \xi_{A_{dk}}, \xi_{I_{dk}}, \xi_{F_{dk}} \rangle = \langle (1, 0, 0) \rangle \tag{3.9}$$

If $d \neq k$

$$\langle \xi_{A_{dk}}, \xi_{I_{dk}}, \xi_{F_{dk}} \rangle = (\langle \min(1, 0 + \tau_{A_{dk}}), \max(0, 1 + \tau_{I_{dk}} - 1), \max(0, 1 + \tau_{F_{dk}} - 1) \rangle)$$

$$= (\langle \min(1, \tau_{A_{dk}}), \max(0, \tau_{I_{dk}}), \max(0, \tau_{F_{dk}}) \rangle)$$

$$\langle \xi_{A_{dk}}, \xi_{I_{dk}}, \xi_{F_{dk}} \rangle = (\langle \xi_{A_{kd}}, \xi_{I_{kd}}, \xi_{F_{kd}} \rangle) \tag{3.10}$$

From (3.8),(3.9) $\Rightarrow \Xi$ is symmetric.

(ii) $\Xi = (\langle \xi_{A_{dk}}, \xi_{I_{dk}}, \xi_{F_{dk}} \rangle)$

$= I_n \wedge_L^* (\Gamma \vee_L^* \Gamma^T)$

$I_n \wedge_L^* (\Gamma \vee_L^* \Gamma^T)$

$$= \begin{cases} (\min(1, 1 + \tau_{A_{dk}}), \max(0, 0 + \tau_{I_{dk}} - 1), \max(0, 0 + \tau_{F_{dk}} - 1)) & \text{if } d = k \\ (\min(1, 0 + \tau_{A_{dk}}), \max(0, 1 + \tau_{I_{dk}} - 1), \max(0, 1 + \tau_{F_{dk}} - 1)) & \text{if } d \neq k \end{cases}$$

If $d = k$

$$\langle \xi_{A_{dk}}, \xi_{I_{dk}}, \xi_{F_{dk}} \rangle = (\langle \min(1, 1 + \tau_{A_{dk}}), \max(0, 0 + \tau_{I_{dk}} - 1), \max(0, 0 + \tau_{F_{dk}} - 1) \rangle)$$

$$\langle \xi_{A_{dk}}, \xi_{I_{dk}}, \xi_{F_{dk}} \rangle = (1, 0, 0)$$

Therefore Ξ is reflexive.

(iii) $I_n \wedge_L^* (\Gamma \vee_L^* \Gamma^T) = I_n \vee (\Gamma \vee_L^* \Gamma^T)$

If $k = d$, then $\langle \xi_{A_{dk}}, \xi_{I_{dk}}, \xi_{F_{dk}} \rangle = (1, 0, 0)$

If $k \neq d$, then $\langle \xi_{A_{dk}}, \xi_{I_{dk}}, \xi_{F_{dk}} \rangle = (\langle \tau_{A_{dk}}, \tau_{I_{dk}}, \tau_{F_{dk}} \rangle)$

$$\Rightarrow I_n \wedge_L^* (\Gamma \vee_L^* \Gamma^T) = I_n \vee (\Gamma \vee_L^* \Gamma^T)$$

Proposition 3.4.

Let Γ, Ψ, Υ be three NFMs.

$$(i) (\Gamma \vee_L^* \Psi) \vee_L^* \Upsilon = \Gamma \vee_L^* (\Psi \vee_L^* \Upsilon)$$

$$(ii) (\Gamma \wedge_L^* \Psi) \wedge_L^* \Upsilon = \Gamma \wedge_L^* (\Psi \wedge_L^* \Upsilon)$$

Proof:

$$\begin{aligned} \text{Let } (\Gamma \vee_L^* \Psi) &= (\langle \tau_{A_{dk}}, \tau_{I_{dk}}, \tau_{F_{dk}} \rangle) \\ (\Psi \vee_L^* \Upsilon) &= (\langle \xi_{A_{dk}}, \xi_{I_{dk}}, \xi_{F_{dk}} \rangle) \\ (\Gamma \vee_L^* \Psi) \vee_L^* \Upsilon &= (\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle) \\ \Gamma \vee_L^* (\Psi \vee_L^* \Upsilon) &= (\langle \varkappa_{A_{dk}}, \varkappa_{I_{dk}}, \varkappa_{F_{dk}} \rangle) \\ &= (\langle \tau_{A_{dk}}, \tau_{I_{dk}}, \tau_{F_{dk}} \rangle) \\ &= (\langle \max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} - 1), \min(1, \gamma_{I_{dk}} + \psi_{I_{dk}}), \min(1, \gamma_{F_{dk}} + \psi_{F_{dk}}) \rangle) \\ &= (\langle \xi_{A_{dk}}, \xi_{I_{dk}}, \xi_{F_{dk}} \rangle) \\ &= (\langle \max(0, \psi_{A_{dk}} + v_{A_{dk}} - 1), \min(1, \psi_{I_{dk}} + v_{I_{dk}}), \min(1, \psi_{F_{dk}} + v_{F_{dk}}) \rangle) \\ (\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle) &= (\langle \max(0, \tau_{A_{dk}} + v_{A_{dk}} - 1), \min(1, \tau_{I_{dk}} + v_{I_{dk}}), \min(1, \tau_{F_{dk}} + v_{F_{dk}}) \rangle) \\ (\langle \varkappa_{A_{dk}}, \varkappa_{I_{dk}}, \varkappa_{F_{dk}} \rangle) &= (\langle \max(0, \gamma_{A_{dk}} + \xi_{A_{dk}} - 1), \min(1, \gamma_{I_{dk}} + \xi_{I_{dk}}), \min(1, \gamma_{F_{dk}} + \xi_{F_{dk}}) \rangle) \end{aligned}$$

$$\text{To Show that } (\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle) = (\langle \varkappa_{A_{dk}}, \varkappa_{I_{dk}}, \varkappa_{F_{dk}} \rangle)$$

Case i) Suppose $\gamma_{A_{dk}} + \psi_{A_{dk}} < 1$; $\gamma_{A_{dk}} + \psi_{A_{dk}} - 1 \leq 0$

And $\gamma_{I_{dk}} + \psi_{I_{dk}} \geq 1$; $\gamma_{F_{dk}} + \psi_{F_{dk}} \geq 1$

$$(\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle) = (\langle \max(0, \tau_{A_{dk}} + v_{A_{dk}} - 1), \min(1, \tau_{I_{dk}} + v_{I_{dk}}), \min(1, \tau_{F_{dk}} + v_{F_{dk}}) \rangle)$$

Suppose $\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} < 1$

$$\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1 < 0; \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} < 1; \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} < 1$$

$$\begin{aligned} (\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle) &= (\langle \max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1 - 1), \min(1, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}}), \\ &\quad \min(1, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}}) \rangle) \\ &= (\langle 0, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}}, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} \rangle) \\ &= (\langle \varkappa_{A_{dk}}, \varkappa_{I_{dk}}, \varkappa_{F_{dk}} \rangle) \end{aligned}$$

1.1) Suppose $\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} < 1$

$$\gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1 \leq 0;$$

Either $\gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} \geq 1$ or $\gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} < 1$;

Either $\gamma_{Fdk} + \psi_{Fdk} + v_{Fdk} \leq 1$ or $\gamma_{Fdk} + \psi_{Fdk} + v_{Fdk} > 1$

$$\begin{aligned} (\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle) &= (\langle \max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1 - 1), \min(1, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}}), \\ &\quad \min(1, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}}) \rangle) \\ &= (\langle 0, 1, 1 \rangle) \\ &= (\langle \varkappa_{A_{dk}}, \varkappa_{I_{dk}}, \varkappa_{F_{dk}} \rangle) \end{aligned}$$

1.2) Suppose $\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} < 1$

$$\begin{aligned} \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1 &\leq 0 ; \\ \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} &\geq 1 \\ \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} &< 1 \\ (\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle) &= (\langle \max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1 - 1), \min(1, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}}), \\ &\quad \min(1, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}}) \rangle) \\ &= (\langle 0, 1, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} \rangle) \\ &= (\langle \varkappa_{A_{dk}}, \varkappa_{I_{dk}}, \varkappa_{F_{dk}} \rangle) \end{aligned}$$

1.3) If $\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} < 1$

$$\begin{aligned} \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1 &\leq 0 ; \\ \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} &< 1 \\ \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} &\geq 1 \text{ then,} \\ (\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle) &= (\langle \max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1 - 1), \min(1, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}}), \\ &\quad \min(1, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}}) \rangle) \\ &= (\langle 0, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}}, 1 \rangle) \\ &= (\langle \varkappa_{A_{dk}}, \varkappa_{I_{dk}}, \varkappa_{F_{dk}} \rangle) \end{aligned}$$

Case 2:

$$\text{If } \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1 > 0$$

$$\begin{aligned} \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} &> 1 \\ \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} &> 1 \text{ then,} \\ (\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle) &= (\langle \max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1), \min(1, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}}), \\ &\quad \min(1, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}}) \rangle) \\ &= (\langle \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1, 1, 1 \rangle) \end{aligned}$$

$$= (\langle \varkappa_{A_{dk}}, \varkappa_{I_{dk}}, \varkappa_{F_{dk}} \rangle)$$

2.1) If $\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1 > 0$

$$\begin{aligned} \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} &< 1 \\ \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} &< 1 \text{ then,} \end{aligned}$$

$$\begin{aligned} (\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle) &= (\langle \max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1), \min(1, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}}), \\ &\quad \min(1, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}}) \rangle) \\ &= (\langle \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}}, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} \rangle) \\ &= (\langle \varkappa_{A_{dk}}, \varkappa_{I_{dk}}, \varkappa_{F_{dk}} \rangle) \end{aligned}$$

2.2) If $\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1 > 0$

$$\begin{aligned} \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} &> 1 \\ \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} &< 1 \text{ then,} \end{aligned}$$

$$\begin{aligned} (\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle) &= (\langle \max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1), \min(1, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}}), \\ &\quad \min(1, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}}) \rangle) \\ &= (\langle \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} - 1, 1, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} \rangle) \\ &= (\langle \varkappa_{A_{dk}}, \varkappa_{I_{dk}}, \varkappa_{F_{dk}} \rangle) \end{aligned}$$

Therefore, in all cases $(\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle) = (\langle \varkappa_{A_{dk}}, \varkappa_{I_{dk}}, \varkappa_{F_{dk}} \rangle)$

$$(\Gamma \vee_L^* \Psi) \vee_L^* \Upsilon = \Gamma \vee_L^* (\Psi \vee_L^* \Upsilon)$$

(ii) Let $(\Gamma \wedge_L^* \Psi) = (\langle \varsigma_{A_{dk}}, \varsigma_{I_{dk}}, \varsigma_{F_{dk}} \rangle)$

$$(\Psi \wedge_L^* \Upsilon) = (\langle \varpi_{A_{dk}}, \varpi_{I_{dk}}, \varpi_{F_{dk}} \rangle)$$

$$(\Gamma \wedge_L^* \Psi) \wedge_L^* \Upsilon = (\langle \nu_{A_{dk}}, \nu_{I_{dk}}, \nu_{F_{dk}} \rangle)$$

$$\Gamma \wedge_L^* (\Psi \wedge_L^* \Upsilon) = (\langle \lambda_{A_{dk}}, \lambda_{I_{dk}}, \lambda_{F_{dk}} \rangle)$$

$$(\langle \varsigma_{A_{dk}}, \varsigma_{I_{dk}}, \varsigma_{F_{dk}} \rangle)$$

$$(\langle \varpi_{A_{dk}}, \varpi_{I_{dk}}, \varpi_{F_{dk}} \rangle)$$

$$= (\langle \min(1, \psi_{A_{dk}} + v_{A_{dk}}), \max(0, \psi_{I_{dk}} + v_{I_{dk}} - 1), \max(0, \psi_{F_{dk}} + v_{F_{dk}} - 1) \rangle)$$

$$(\langle \nu_{A_{dk}}, \nu_{I_{dk}}, \nu_{F_{dk}} \rangle)$$

$$= (\langle \min(1, \varsigma_{A_{dk}} + v_{A_{dk}}), \max(0, \varsigma_{I_{dk}} + v_{I_{dk}} - 1), \max(0, \varsigma_{F_{dk}} + v_{F_{dk}} - 1) \rangle)$$

$$\begin{aligned} & (\langle \lambda_{A_{dk}}, \lambda_{I_{dk}}, \lambda_{F_{dk}} \rangle) \\ & = (\langle \min(1, \gamma_{A_{dk}} + \varpi_{A_{dk}}), \max(0, \gamma_{I_{dk}} + \varpi_{I_{dk}} - 1), \max(0, \gamma_{F_{dk}} + \varpi_{F_{dk}} - 1) \rangle) \end{aligned}$$

To Show that $(\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) = (\langle \lambda_{A_{dk}}, \lambda_{I_{dk}}, \lambda_{F_{dk}} \rangle)$

Case i) Suppose $\gamma_{A_{dk}} + \psi_{A_{dk}} < 1$; $\gamma_{A_{dk}} + \psi_{A_{dk}} - 1 \leq 0$

And $\gamma_{I_{dk}} + \psi_{I_{dk}} \geq 1$; $\gamma_{F_{dk}} + \psi_{F_{dk}} \geq 1$

$$\begin{aligned} & (\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) \\ & = (\langle \min(1, \varsigma_{A_{dk}} + v_{A_{dk}}), \max(0, \varsigma_{I_{dk}} + v_{I_{dk}} - 1), \max(0, \varsigma_{F_{dk}} + v_{F_{dk}} - 1) \rangle) \end{aligned}$$

Suppose $\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} < 1$

$\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} < 1$; $\gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1 < 0$; $\gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} - 1 < 0$

$$\begin{aligned} (\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) & = \left(\min(1, \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}}), \max(0, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1), \right. \\ & \quad \left. \max(0, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} - 1) \right) \\ & = (\langle \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}}, 0, 0 \rangle) \\ & = (\langle \lambda_{A_{dk}}, \lambda_{I_{dk}}, \lambda_{F_{dk}} \rangle) \end{aligned}$$

1.4) Suppose $\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} < 1$;

Either $\gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} \geq 1$ or $\gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} < 1$;

Either $\gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} \geq 1$ or $\gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} < 1$

$$\begin{aligned} (\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) & = \left(\min(1, \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}}), \max(0, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1 - 1), \right. \\ & \quad \left. \max(0, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} - 1 - 1) \right) \\ & = (\langle \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}}, 1, 1 \rangle) \\ & = (\langle \lambda_{A_{dk}}, \lambda_{I_{dk}}, \lambda_{F_{dk}} \rangle) \end{aligned}$$

1.5) Suppose $\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} < 1$

$\gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1 \geq 0$

$\gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} - 1 - 1 < 0$

$$\begin{aligned} (\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) & = \left(\min(1, \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}}), \max(0, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1 - 1), \right. \\ & \quad \left. \max(0, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} - 1 - 1) \right) \\ & = (\langle \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}}, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1, 0 \rangle) \end{aligned}$$

$$= (\langle \lambda_{A_{dk}}, \lambda_{I_{dk}}, \lambda_{F_{dk}} \rangle)$$

1.6) If $\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} < 1$

$$\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} \leq 0 ;$$

$$\gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1 < 0$$

$$\gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} - 1 \geq 0 \text{ then,}$$

$$(\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) = \left(\min(1, \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}}), \max(0, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1 - 1), \right. \\ \left. \max(0, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} - 1 - 1) \right)$$

$$= (\langle \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}}, 0, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} - 1 \rangle)$$

$$= (\langle \lambda_{A_{dk}}, \lambda_{I_{dk}}, \lambda_{F_{dk}} \rangle)$$

Case 2:

If $\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} > 1$

$$\gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1 > 0$$

$$\gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} - 1 > 0 \text{ then,}$$

$$(\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) = \left(\min(1, \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}}), \max(0, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1 - 1), \right. \\ \left. \max(0, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} - 1 - 1) \right)$$

$$= (\langle 1, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} - 1 \rangle)$$

$$= (\langle \lambda_{A_{dk}}, \lambda_{I_{dk}}, \lambda_{F_{dk}} \rangle)$$

2.1) If $\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} > 1$

$$\gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1 < 0$$

$$\gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} - 1 < 0 \text{ then,}$$

$$(\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) = \left(\min(1, \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}}), \max(0, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1 - 1), \right. \\ \left. \max(0, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} - 1 - 1) \right)$$

$$= (\langle \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}}, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} - 1 \rangle)$$

$$= (\langle \lambda_{A_{dk}}, \lambda_{I_{dk}}, \lambda_{F_{dk}} \rangle)$$

2.2) If $\gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}} > 1$

$$\gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1 > 0$$

$\gamma_{Fdk} + \psi_{Fdk} + v_{Fdk} - 1 < 0$ then,

$$\begin{aligned} (\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) &= \left(\min(1, \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}}), \max(0, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1 - 1), \right. \\ &\quad \left. \max(0, \gamma_{F_{dk}} + \psi_{F_{dk}} + v_{F_{dk}} - 1 - 1) \right) \\ &= (\langle \gamma_{A_{dk}} + \psi_{A_{dk}} + v_{A_{dk}}, \gamma_{I_{dk}} + \psi_{I_{dk}} + v_{I_{dk}} - 1, 0 \rangle) \\ &= (\langle \lambda_{A_{dk}}, \lambda_{I_{dk}}, \lambda_{F_{dk}} \rangle) \end{aligned}$$

Therefore, in all cases

$$(\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) = (\langle \lambda_{A_{dk}}, \lambda_{I_{dk}}, \lambda_{F_{dk}} \rangle)$$

$$(\Gamma \wedge_L^* \Psi) \wedge_L^* Y = \Gamma \wedge_L^* (\Psi \wedge_L^* Y)$$

Proposition 3.5.

Let Γ, Ψ, Y be three NFMs. Then $\Gamma \vee_L^* (\Psi \vee Y) = (\Gamma \vee_L^* \Psi) \vee (\Gamma \vee_L^* Y)$

Proof:

$$\text{Let } (\Psi \vee Y) = (\langle \varkappa_{A_{dk}}, \varkappa_{I_{dk}}, \varkappa_{F_{dk}} \rangle); (\Gamma \vee_L^* \Psi) = (\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle)$$

$$(\Gamma \vee_L^* Y) = (\langle \tau_{A_{dk}}, \tau_{I_{dk}}, \tau_{F_{dk}} \rangle)$$

$$\Gamma \vee_L^* (\Psi \vee Y) = (\langle \omega_{A_{dk}}, \omega_{I_{dk}}, \omega_{F_{dk}} \rangle)$$

$$(\Gamma \vee_L^* \Psi) \vee (\Gamma \vee_L^* Y) = (\langle \lambda_{A_{dk}}, \lambda_{I_{dk}}, \lambda_{F_{dk}} \rangle)$$

$$\text{Now, } (\langle \varkappa_{A_{dk}}, \varkappa_{I_{dk}}, \varkappa_{F_{dk}} \rangle) = (\langle (\max(\psi_{A_{dk}}, v_{A_{dk}}), \min(\psi_{I_{dk}}, v_{I_{dk}}), \min(\psi_{F_{dk}}, v_{F_{dk}})) \rangle)$$

$$(\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle)$$

$$= (\langle (\max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} - 1), \min(1, \gamma_{I_{dk}} + \psi_{I_{dk}}), \min(1, \gamma_{F_{dk}} + \psi_{F_{dk}})) \rangle)$$

$$(\langle \tau_{A_{dk}}, \tau_{I_{dk}}, \tau_{F_{dk}} \rangle)$$

$$= (\langle (\max(0, \gamma_{A_{dk}} + v_{A_{dk}} - 1), \min(1, \gamma_{I_{dk}} + v_{I_{dk}}), \min(1, \gamma_{F_{dk}} + v_{F_{dk}})) \rangle)$$

$$(\langle \omega_{A_{dk}}, \omega_{I_{dk}}, \omega_{F_{dk}} \rangle) = (\langle \max(0, \gamma_{A_{dk}} + \varkappa_{A_{dk}} - 1), \min(1, \gamma_{I_{dk}} +$$

$$\varkappa_{I_{dk}}), \min(1, \gamma_{F_{dk}} + \varkappa_{F_{dk}}) \rangle) \quad (3.11)$$

$$(\langle \lambda_{A_{dk}}, \lambda_{I_{dk}}, \lambda_{F_{dk}} \rangle) =$$

$$(\langle \max(\sigma_{A_{dk}}, \tau_{A_{dk}}), \min(\sigma_{I_{dk}}, \tau_{I_{dk}}), \min(\sigma_{F_{dk}}, \tau_{F_{dk}}) \rangle) \quad (3.12)$$

We have to prove (1) = (2)

Case 1)

Suppose

$$(\langle \psi_{A_{dk}}, \psi_{I_{dk}}, \psi_{F_{dk}} \rangle) \leq (\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) \quad (3.13)$$

$$\text{Then, } (\langle \varkappa_{A_{dk}}, \varkappa_{I_{dk}}, \varkappa_{F_{dk}} \rangle) = (\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle)$$

$$(\langle \omega_{A_{dk}}, \omega_{I_{dk}}, \omega_{F_{dk}} \rangle)$$

$$= (\langle \max(0, \gamma_{A_{dk}} + \varkappa_{A_{dk}} - 1), \min(1, \gamma_{I_{dk}} + \varkappa_{I_{dk}}), \min(1, \gamma_{F_{dk}} + \varkappa_{F_{dk}}) \rangle)$$

Either $\gamma_{A_{dk}} + \varkappa_{A_{dk}} - 1 \geq 0$ or $\gamma_{A_{dk}} + \varkappa_{A_{dk}} < 1$

$\gamma_{I_{dk}} + \varkappa_{I_{dk}} \geq 1$ and $\gamma_{F_{dk}} + \varkappa_{F_{dk}} \geq 1$

$$(\langle \omega_{A_{dk}}, \omega_{I_{dk}}, \omega_{F_{dk}} \rangle) = (\gamma_{A_{dk}} + \varkappa_{A_{dk}} - 1, 1, 1) \quad (3.14)$$

$$\text{Now, } (\langle \lambda_{A_{dk}}, \lambda_{I_{dk}}, \lambda_{F_{dk}} \rangle) = (\max(\sigma_{A_{dk}}, \tau_{A_{dk}}), \min(\sigma_{I_{dk}}, \tau_{A_{dk}}), \min(\sigma_{A_{dk}}, \tau_{A_{dk}}))$$

Here,

$$\begin{aligned} & (\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle) \\ &= (\langle \max(0, \gamma_{A_{dk}} + \psi_{A_{dk}} - 1), \min(1, \gamma_{I_{dk}} + \psi_{I_{dk}}), \min(1, \gamma_{F_{dk}} + \psi_{F_{dk}}) \rangle) \\ & \text{If } \gamma_{A_{dk}} + \psi_{A_{dk}} - 1 \geq 0, \gamma_{I_{dk}} + \psi_{I_{dk}} \geq 1 \text{ and } \gamma_{F_{dk}} + \psi_{F_{dk}} \geq 1 \text{ then} \\ & (\langle \sigma_{A_{dk}}, \sigma_{I_{dk}}, \sigma_{F_{dk}} \rangle) = (\gamma_{A_{dk}} + \psi_{A_{dk}} - 1, 1, 1) \end{aligned} \quad (3.15)$$

If $\gamma_{A_{dk}} + v_{A_{dk}} - 1 > 0, \gamma_{I_{dk}} + v_{I_{dk}} \geq 1$ and $\gamma_{F_{dk}} + v_{F_{dk}} \geq 1$ then

$$\begin{aligned} & (\langle \tau_{A_{dk}}, \tau_{I_{dk}}, \tau_{F_{dk}} \rangle) \\ &= (\langle \max(0, \gamma_{A_{dk}} + v_{A_{dk}} - 1), \min(1, \gamma_{I_{dk}} + v_{I_{dk}}), \min(1, \gamma_{F_{dk}} + v_{F_{dk}}) \rangle) \\ &= (\gamma_{A_{dk}} + v_{A_{dk}} - 1, 1, 1) \\ & (\Gamma \vee_L^* \Psi) \vee (\Gamma \vee_L^* \Upsilon) \\ &= (\langle \max((\gamma_{A_{dk}} + \psi_{A_{dk}} - 1), \gamma_{A_{dk}} + v_{A_{dk}} - 1), \min(1, 1), \min(1, 1) \rangle) \end{aligned}$$

By eq (3.13)

$$\begin{aligned} & (\langle \lambda_{A_{dk}}, \lambda_{I_{dk}}, \lambda_{F_{dk}} \rangle) = (\gamma_{A_{dk}} + v_{A_{dk}} - 1, 1, 1) \\ & (3.16) \\ &= (\gamma_{A_{dk}} + \varkappa_{A_{dk}} - 1, 1, 1) \end{aligned}$$

Therefore (3.13) = (3.16)

$$\begin{aligned} & \text{Similarly, we can prove for } (\langle \psi_{A_{dk}}, \psi_{I_{dk}}, \psi_{F_{dk}} \rangle) \geq (\langle v_{A_{dk}}, v_{I_{dk}}, v_{F_{dk}} \rangle) \\ & \Rightarrow \Gamma \vee_L^* (\Psi \vee \Upsilon) = (\Gamma \vee_L^* \Psi) \vee (\Gamma \vee_L^* \Upsilon) \end{aligned}$$

4. Conclusion

Here we overcome some properties of Lukasiewicz over NFMs. Also, we worked commutative, reflexive, irreflexive over \vee_L^* and \wedge_L^* . We developed \vee_L^* and \wedge_L^* in NFMs. In day today life we are facing any problem in indeterministic form. These and all solved using neutrosophic fuzzy sets and matrices. Here we solved some property using max, min, min and min, max, max in NFMs. And also, we travelled with Lukasiewicz concepts in NFMs.

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